

Fair and efficient taxation under partial control

Erwin Ooghe & Andreas Peichl

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- *Fairness* plays a role in redistribution:
 - the more an outcome is determined by 'luck' (resp. 'effort')
 - the more (resp. less) redistribution is preferred
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 - under partial control [and lots of assumptions]

Individual preferences/constraints

- Utility $U(c, \mathbf{x}, \mathbf{e})$ is a function of
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- Individuals solve

$$\max_{\mathbf{e}} U(c, \mathbf{x}, \mathbf{e}) \text{ s.t. } c \leq y - \tau(y, \mathbf{x}) \ \& \ (y, \mathbf{x}) = f(\mathbf{e}).$$

Simplifying assumptions

- quasi-linear & additive structure on utility:
 - $U(c, \mathbf{x}, \mathbf{e}) = c + \sum_{j=1}^J \beta_j x_j - h(\mathbf{e})$, with
 - $h(\mathbf{e}) = \sum_{j=0}^J \frac{\delta_j}{\exp \gamma_j} \exp\left(\frac{e_j}{\delta_j}\right)$.

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- $y = \alpha_0 e_0 + (1 - \alpha_0)\theta_0$, and

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- Unobserved abilities and tastes:
 - $\boldsymbol{\theta} = (\theta_0, \theta_1, \dots, \theta_J)$ is $N(\boldsymbol{\mu}^\theta, \boldsymbol{\Sigma}^\theta)$
 - $\boldsymbol{\gamma} = (\gamma_0, \gamma_1, \dots, \gamma_J)$ is $N(\boldsymbol{\mu}^\gamma, \boldsymbol{\Sigma}^\gamma)$

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- The planner solves

$$\max_{\tau} W(\tau) \text{ s.t. } R(\tau) \geq R_0,$$

with R_0 an exogenous (per-capita) revenue requirement.

Simplifying assumptions

- Welfare is the 'average transformed well-being', i.e.,

$$W(\tau) = \phi^{-1}[\int_{\theta} \int_{\gamma} \phi(v(\tau, \theta, \gamma)) dF(\theta) dG(\gamma)],$$

with ϕ exponential, i.e., $\phi(x) = \exp(-rx)$.

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- Taxation is linear, so

$$\tau(y, \mathbf{x}) = T + t_0 y + \sum_{j=1}^J t_j x_j.$$

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- Pareto: higher utilities are reflected in higher welfare
- Compensation (for abilities): a PD transfer between individuals with the same tastes improves social welfare
- Responsibility (for tastes): if all individuals have the same ability, then the laissez-faire should result ($\tau^* = R_0$)

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Tax up to the point where:

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 - taste heterogeneity & responsibility
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We focus on two special cases—income only & adding a tag to income—before discussing the general case in more detail.

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- decreases with the degree of control α_0 .

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$$t_1^* = \beta_1 + (1 - t_0^*)(1 - \alpha_0)\sigma_{01}^\theta / \sigma_{11}^\theta,$$

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so, it should be higher

- the higher the direct effect β_1 of the tag on well-being
- the higher the signal σ_{01}^θ . [+ other; see paper]

Towards testable conditions

- Recall that the optimal tax on the tag t_1^* should satisfy

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- In particular, $\text{cov}(x_1, y) / \text{cov}(x_1, x_1)$ is an OLS estimate, so
 - β_1 is the direct effect of the tag on well-being, and
 - $(1 - t_0^*) \times \text{cov}(x_1, y) / \text{cov}(x_1, x_1)$ is $E[\text{indirect effect}]$.

Testable conditions

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- Consider data collected in:
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 - a $n \times |P|$ matrix \mathbf{X}_P for the partially controllable factors.
- We obtain that the optimal tax rates t_j^* , for j in N , are

$$\mathbf{t}_N^* = \boldsymbol{\beta}_N + (1 - t_0)(\mathbf{X}'_N \mathbf{X}_N)^{-1} \mathbf{X}'_N \mathbf{y} + (\mathbf{X}'_N \mathbf{X}_N)^{-1} \mathbf{X}'_N \mathbf{X}_P (\boldsymbol{\beta}_P - \mathbf{t}_P).$$

[implementation + link with 'EoP'-literature]